

The BCM1F Detector: commissioning at LHC Run II and first results.

Olena Karacheban
on behalf of the Beam Radiation Instrumentation
and Luminosity group (BRIL) of CMS

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Outline

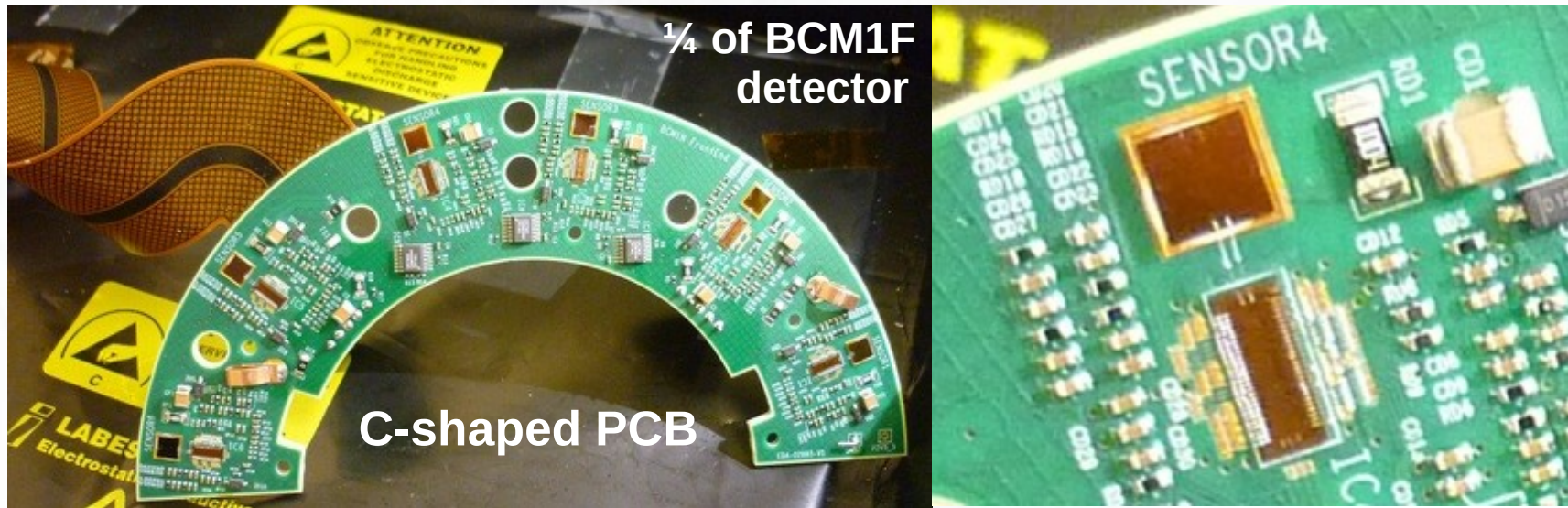
Part 1

- **The BCM1F detector and back end electronics.**
- **Detector performance plots and efficiency monitoring:**
 - Radiation damage of the sensors;
 - Radiation damage of the electronics;
 - Effects in the metallization gap and non metallized edges.
- **HV instability issues.**
- **Long pulses and anomalous spikes.**

Part 2

- **BCM1F as Luminometer:**
 - Calibration and Van der Meer scan

Fast Beam Condition Monitor (BCM1F) based on diamond sensors

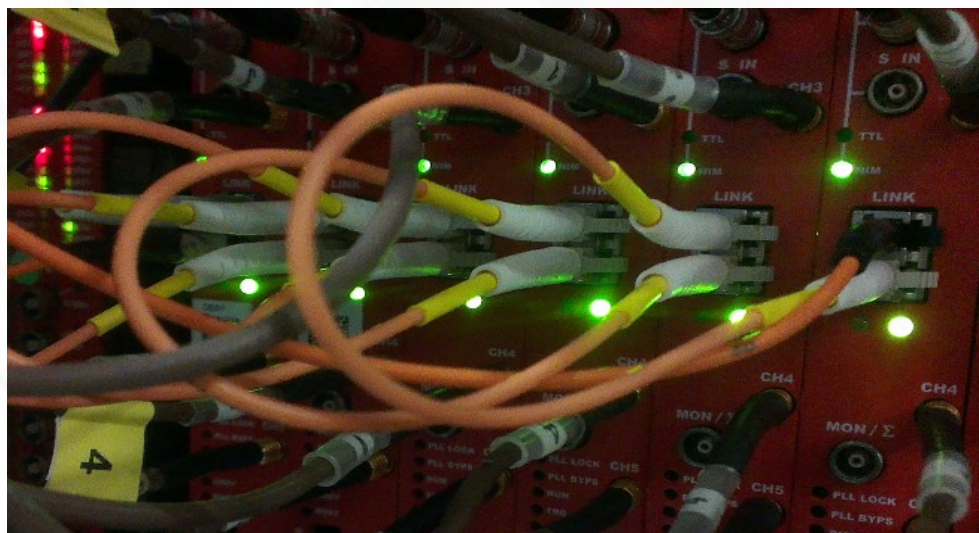
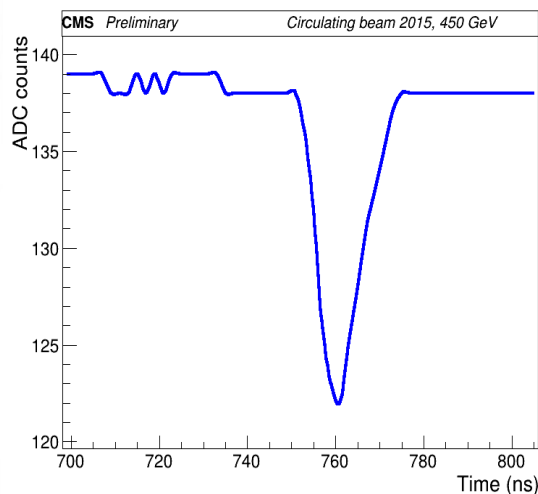


- 2 C-shaped PCB from both ends of CMS, 1.8 m from interaction point;
- 6 diamond sensors with 2 pad metallization per C-shape — 12 channels;
- Signals are preamplified with radiation hard ASIC 130nm technology;
- The electrical signal is converted into an optical signal which is then transmitted to the backend electronics in counting room (USC55).
- From optical receivers data is provided to 3 recording systems: Real-time Histogramming Unit (RHU), uTCA ADCs and VME ADCs.

More information about the BCM1F detector in M.Hempel talk.

Back end: VME ADCs

- 48 channels of BCM1F are served by CAEN v1721 ADCs:
 - 8 channels 8 bit 500 MS/s Digitizer (2 ns sampling time);
- 6 ADC boards are daisy chained and read out via optical link with transfer rate up to 80MB/s.
- Whole LHC orbit (89 μ s) is buffered for each channel:
 - Clock: internal;
 - Trigger for readout: external - LHC orbit clock.
- Sampled data is recorded on the server and processed offline.



Easter present: beam splashes at LHC!

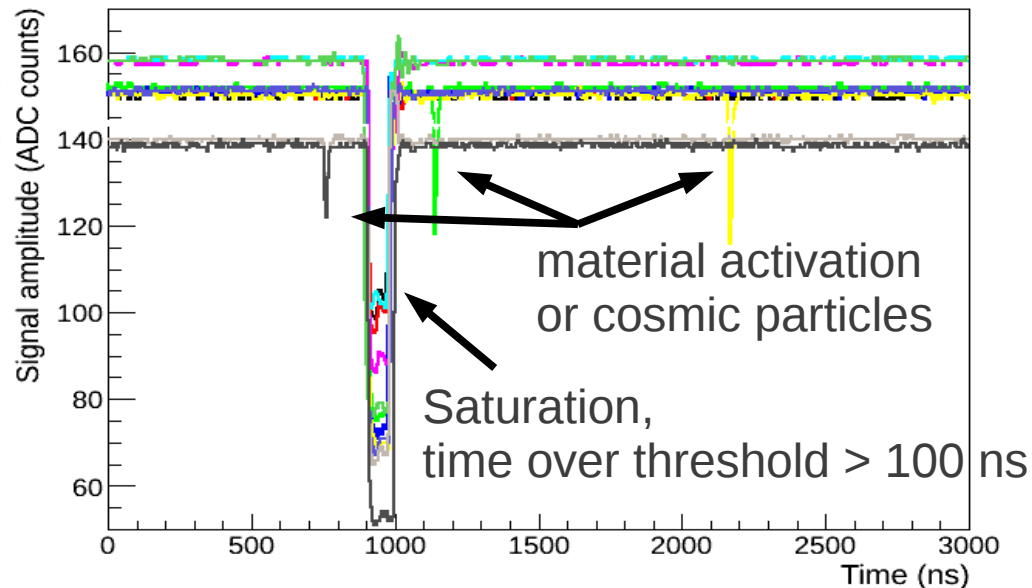


CMS Preliminary

Beam Splash 2015, 450 GeV

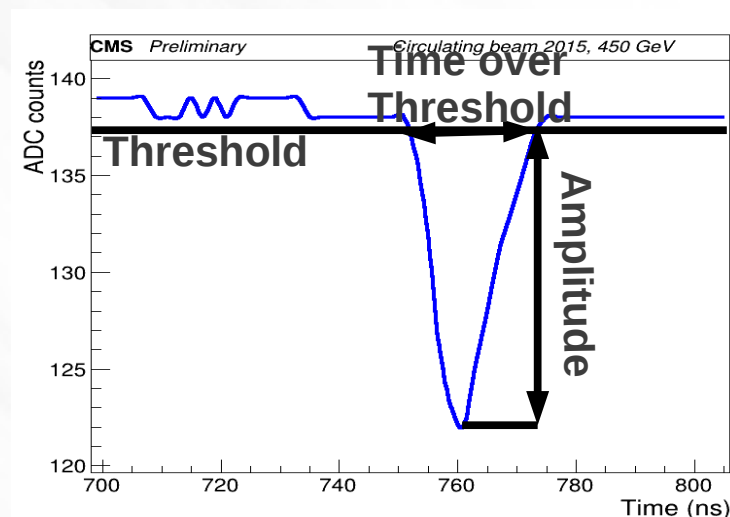
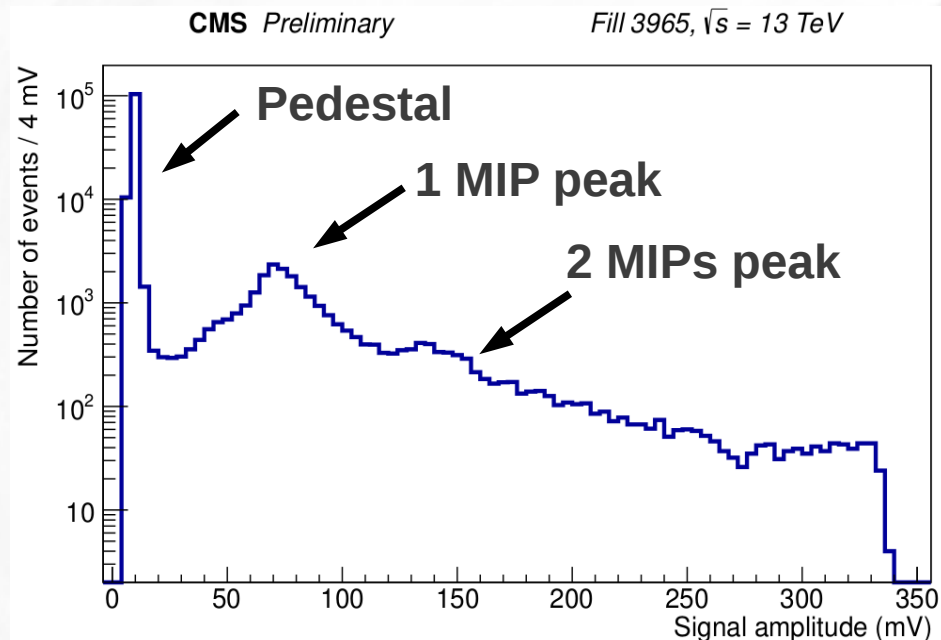


- Splash event: a single bunch is dumped in a collimator just upstream of the experiment.
- Since many particles cross the sensor simultaneously the signal amplitude saturates.
- First data recorded by the VME ADCs: the response of diamond sensors in splash events.



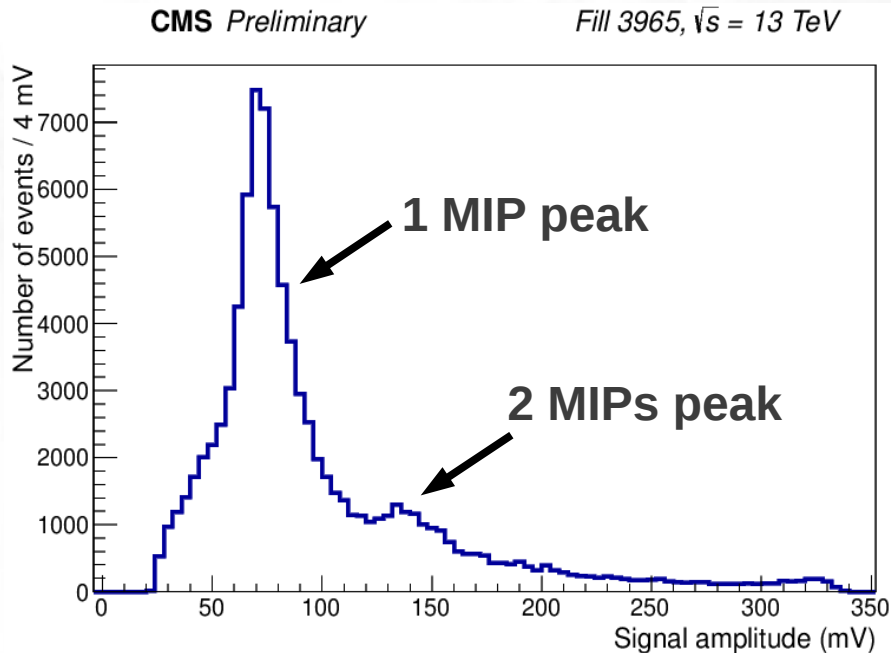
Peak finding algorithm

- ADC data is used to monitor:
 - baseline stability;
 - signal amplitude and length;
 - stability of MIP peak position;
 - Test pulse (TP) amplitude.
- Required parameters in the offline data processing:
 - threshold and minimum time over threshold.



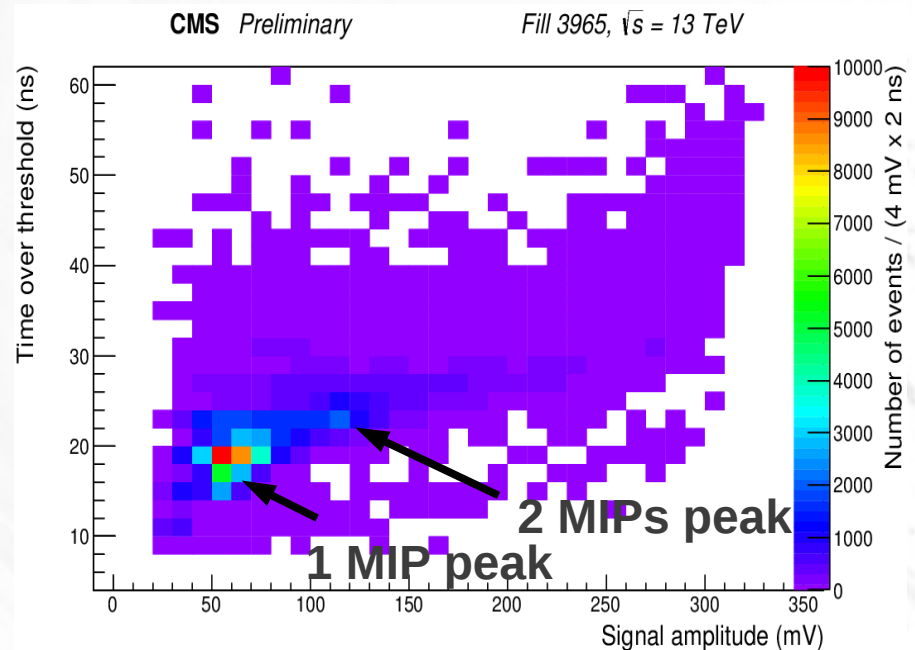
Performance plots

BCM1F amplitude spectrum.



- HV: 200 V (CCE 100%).
- Signal amplitude cut: $A > 20$ mV.

Time over threshold vs. signal amplitude.



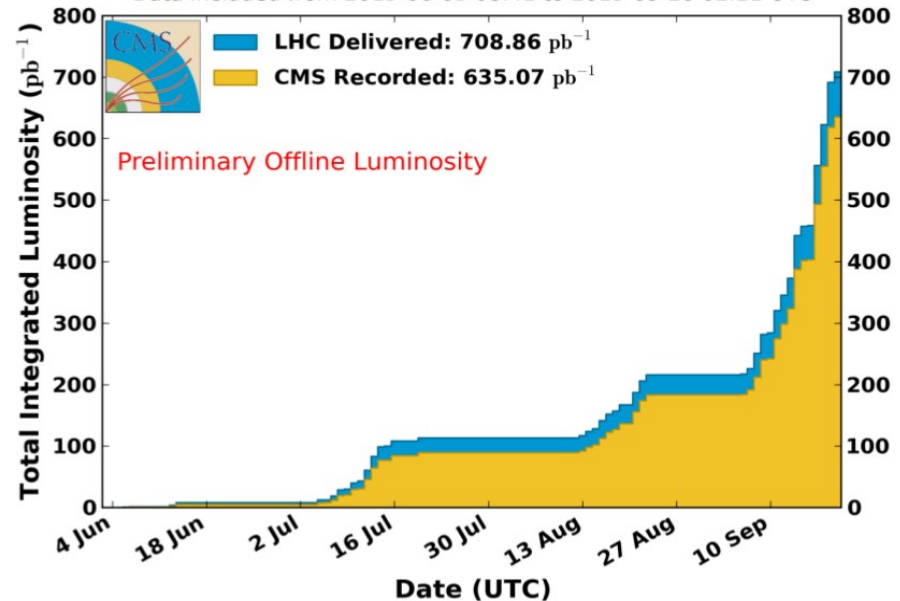
- The fraction of pulses with time over threshold > 25 ns (LHC bunch spacing) is in the range 10-25%, for this particular channel 22%.

MIP amplitude spectrum

- Radiation damage of the sensor cause:
 - (*) slight decrease of MIP peak position;
 - (**) increased number of signals with lower amplitude (confirmed in Test beam data analysis).

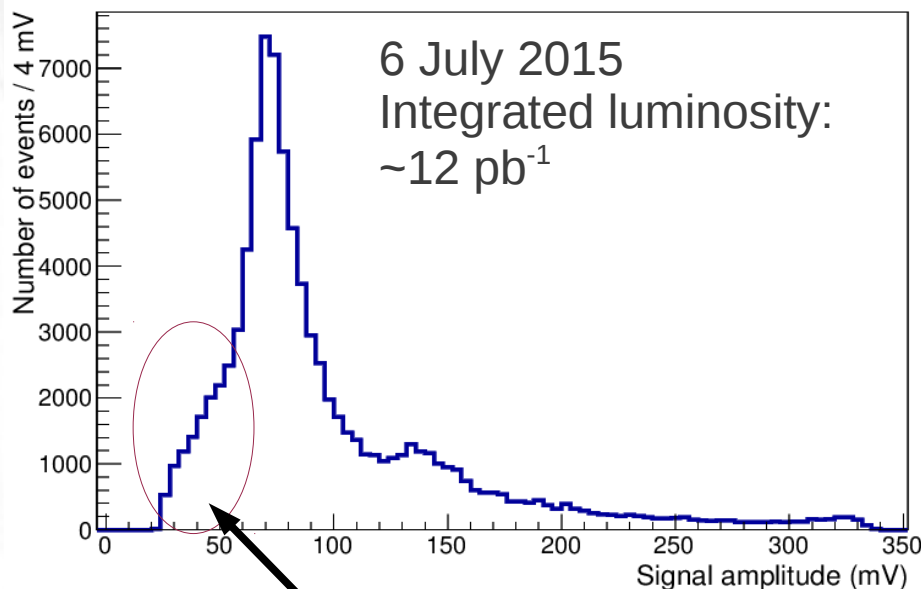
CMS Integrated Luminosity, pp, 2015, $\sqrt{s} = 13$ TeV

Data included from 2015-06-03 08:41 to 2015-09-20 02:21 UTC



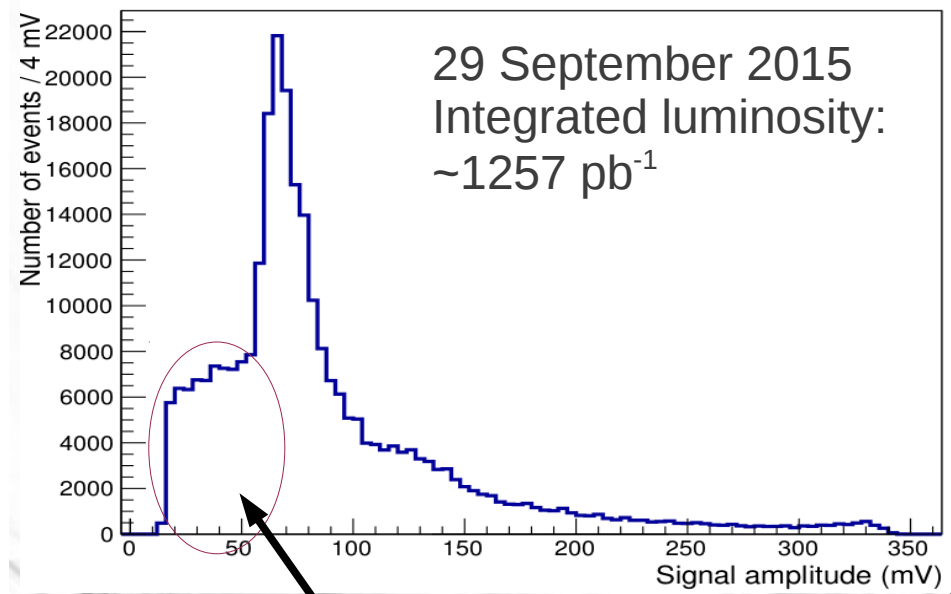
CMS Preliminary

Fill 3965, $\sqrt{s} = 13$ TeV



CMS Preliminary

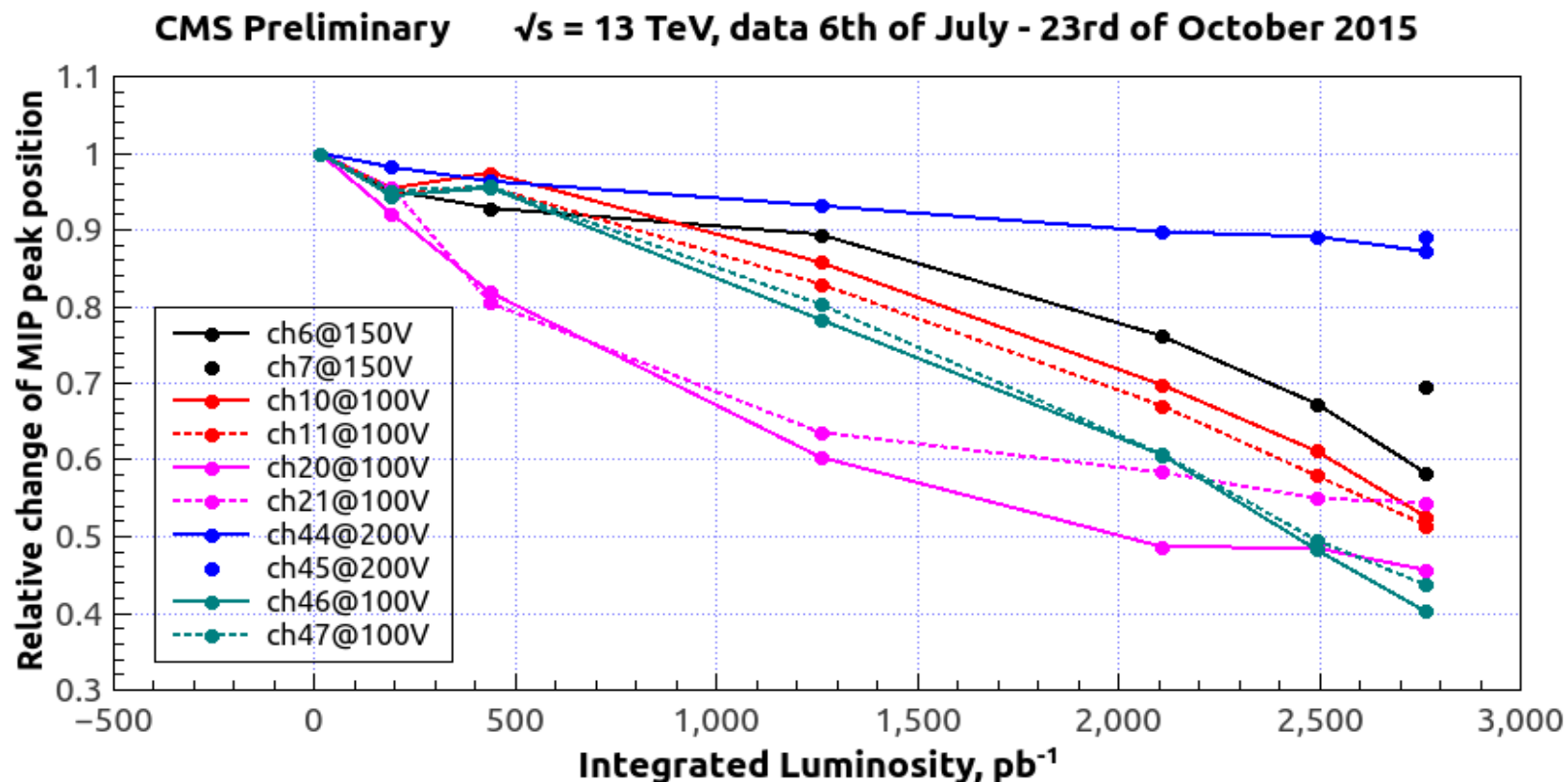
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For the better understanding of the spectrum, Test beam data analysis required.

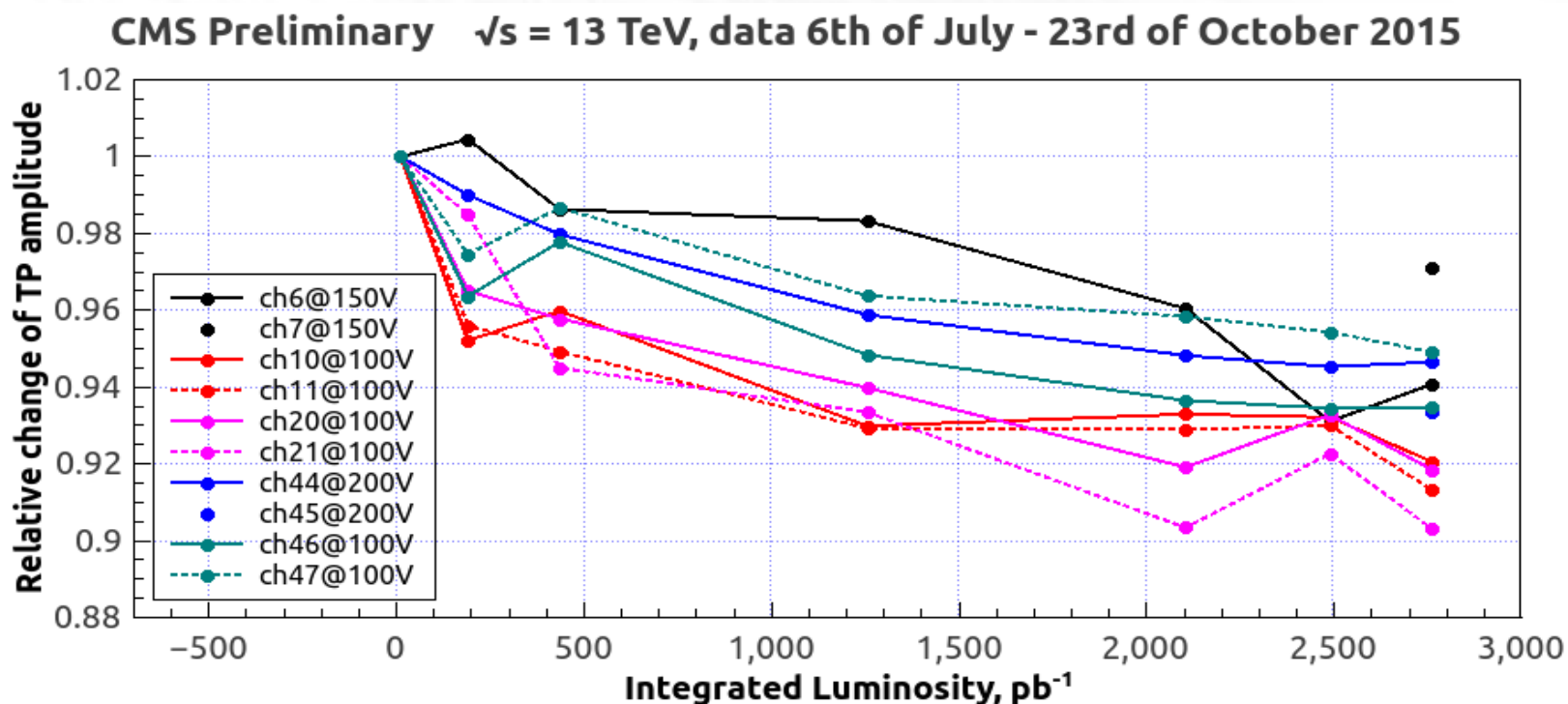
Decrease of MIP peak position (*)

- The signal amplitude spectrum of detected particles is built using a peak finding algorithm. Landau fit is used to define most probable value (MPV) of the spectrum.
- **Relative drop of MIP peak position from the beginning of operation in Run II is up to 60 % in investigated channels.** (ch44-45 are reference channels with $\sim 10\%$ relative drop).
- Observed drop: sensors damage + electronics damage (defined from TP).



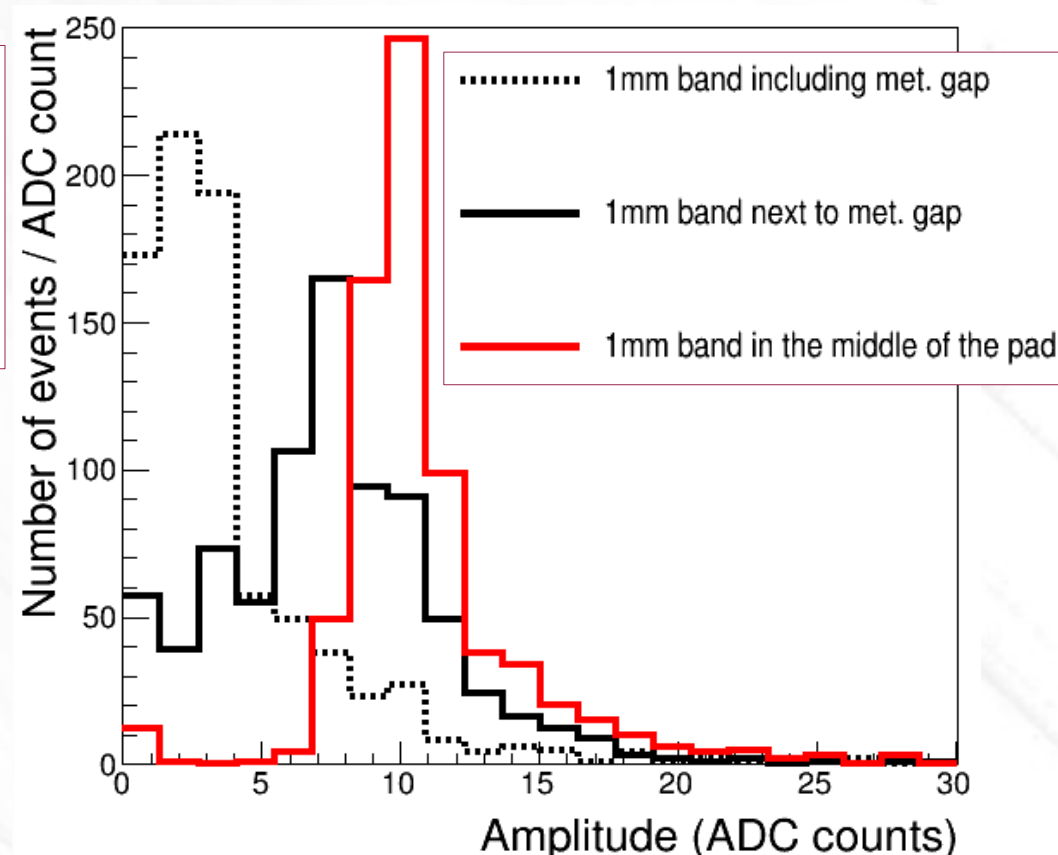
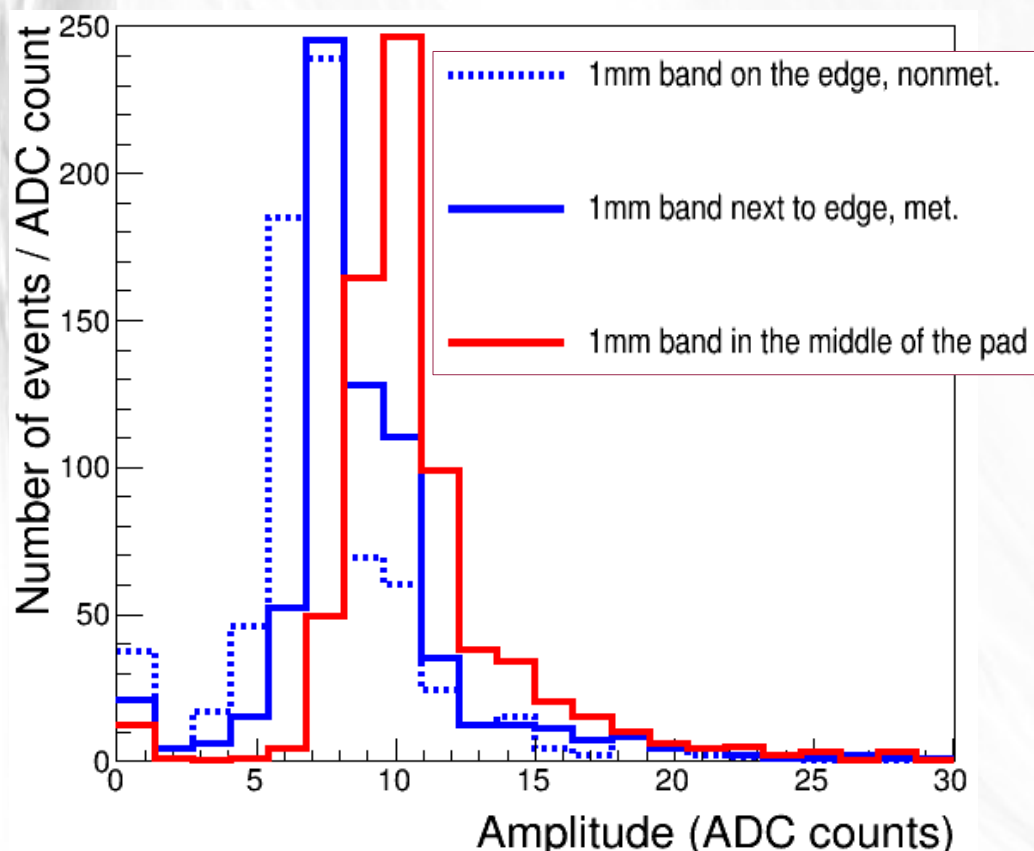
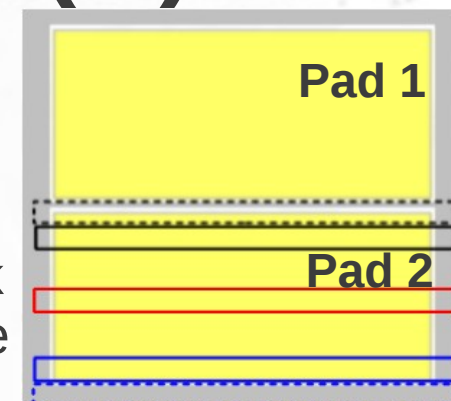
Electronics chain stability monitoring (*)

- Test pulse of known amplitude is generated in the ASIC in the abort gap of the LHC. It is used for monitoring of performance of the electronics chain.
- The signal amplitude spectrum for TP is built using a peak finding algorithm, the same as for the MIP spectrum. Gaussian fit is used to define mean value of the spectrum.
- **Relative drop of TP amplitude from the beginning of operation in Run II is <10% for investigated channels.**
- **The typical loss of signal due to the sensor is up to 50% and due to the electronics is up to 10%.**



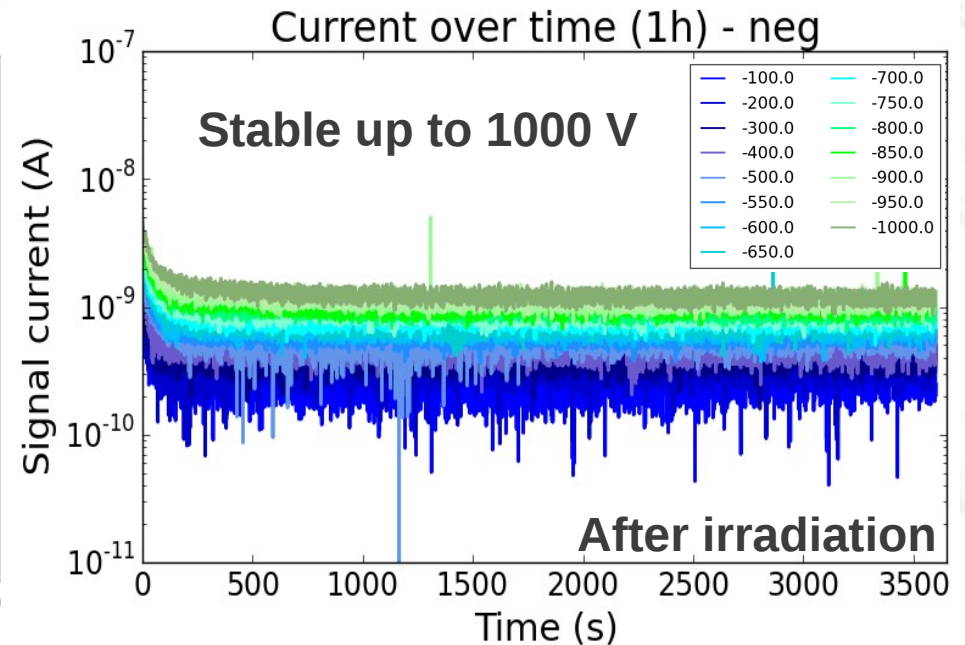
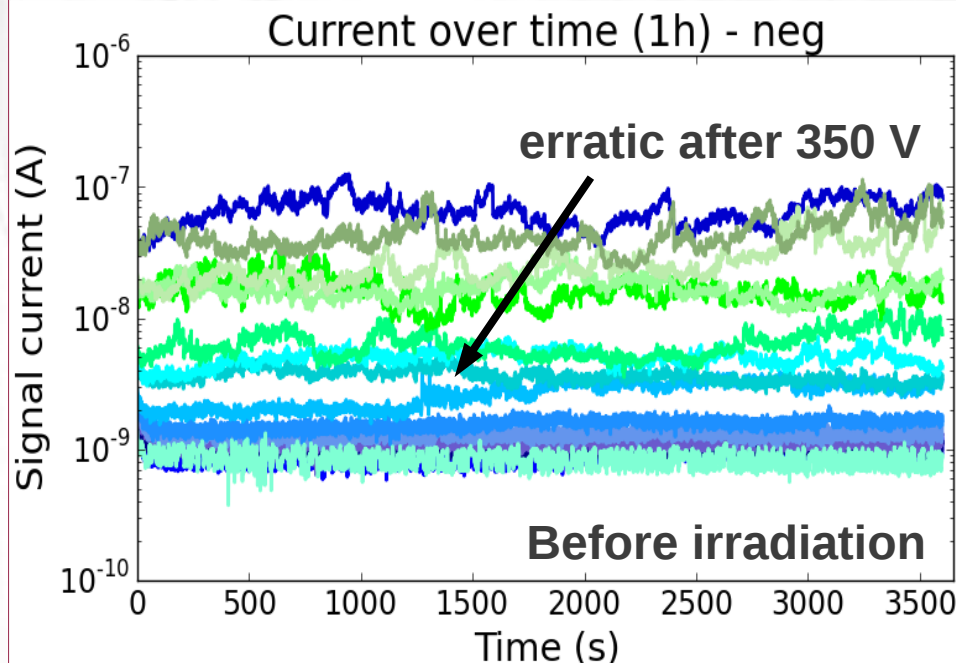
Test Beam data analysis (**)

- Hits from narrow 1 mm bands on the edge of the diamond sensor and containing the metallization gap were selected using EUDET Telescope track pointing information.
- The amplitude spectrums from non metallized area has peak at smaller values. This effect is even more pronounced in the metallization gap.



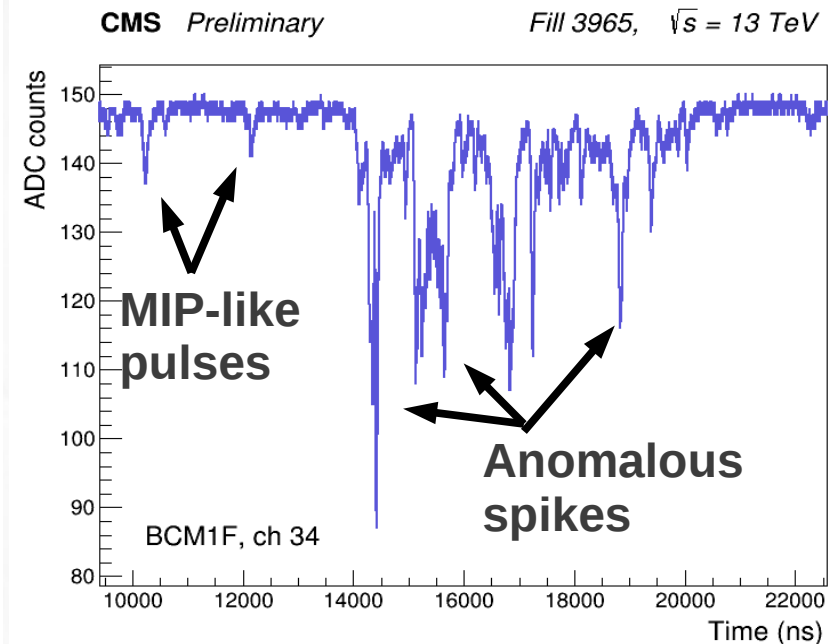
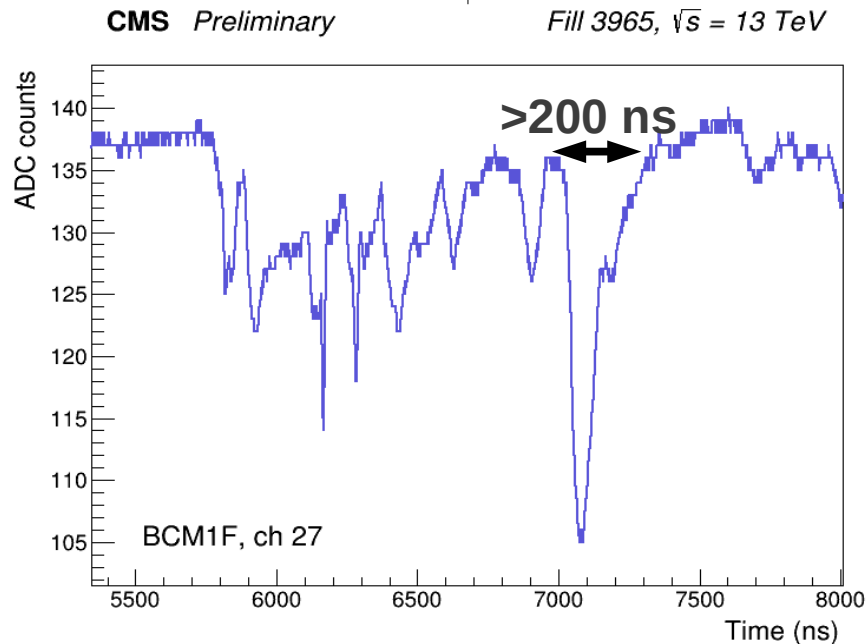
HV instability

- To compensate for radiation damage, HV should be increased.
- For some of the BCM1F channels **HV trips happen**: it was not a case at the beginning of operation. These channels were stable at the same HV. Trip threshold 3 μA .
- Also magnetic field influence HV, which sensors can hold. With **Magnetic field off** HV should be lowered for 50-100V.
- Studies of sCVD diamonds behavior after irradiation at KIT show increase of the stability with irradiation for the majority of sensors.



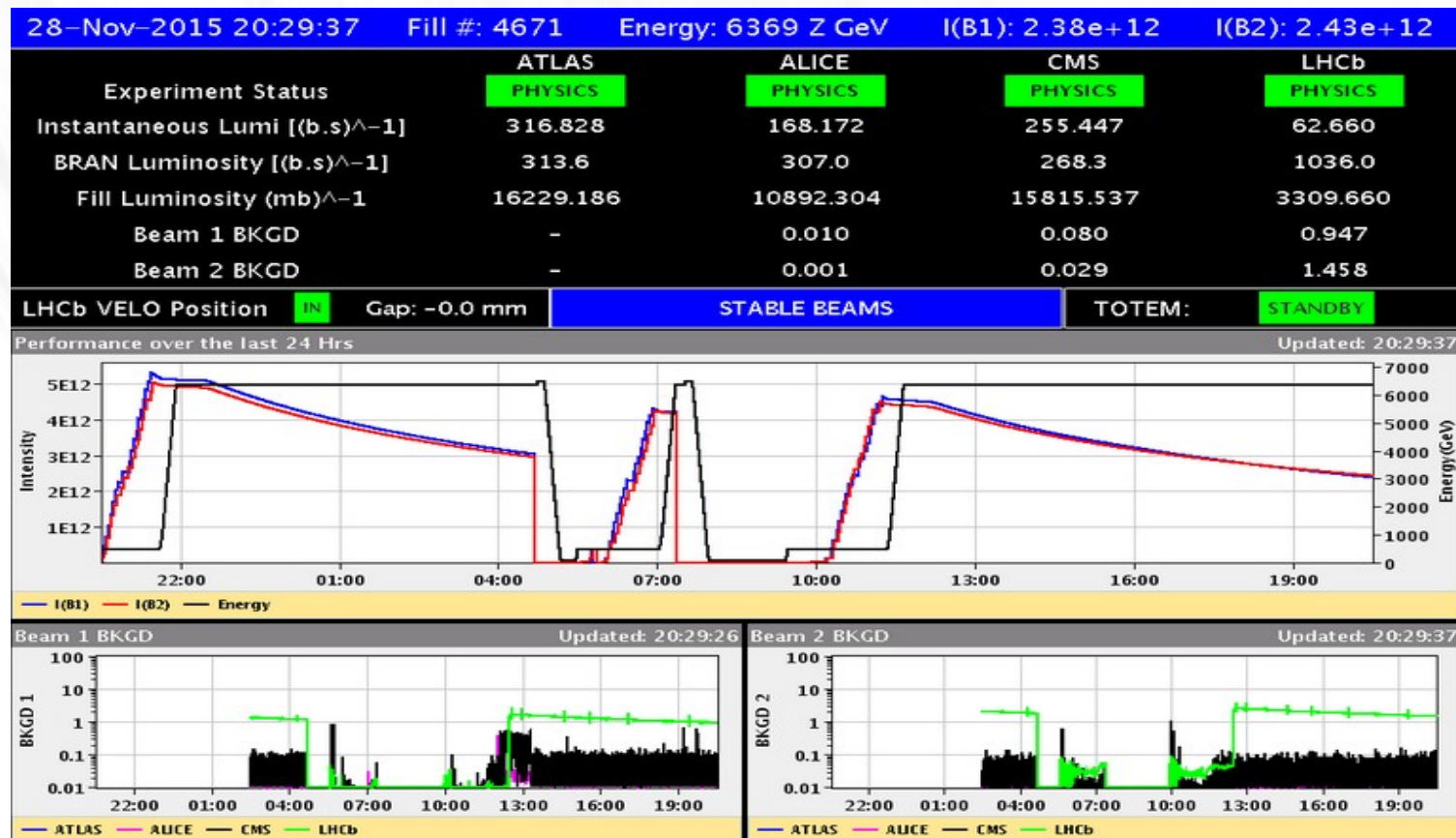
Plots: F. Kassel, Irradiation campaign 2015 at KIT.

Long pulses and anomalous spikes



- Data corresponds to the low luminosity beam in the LHC, no saturation of the electronics or particle hits one after another are expected.
- Full width at half maximum (FWHM) of the pulse generated by Minimum ionising particle (MIP) is expected to be ~ 10 ns.
- Currently orbits, containing such long events are excluded from analysis. Fraction of excluded orbits in Fill 3965 is $< 1\%$.

Part 2: ONLINE Luminosity and Background measurements



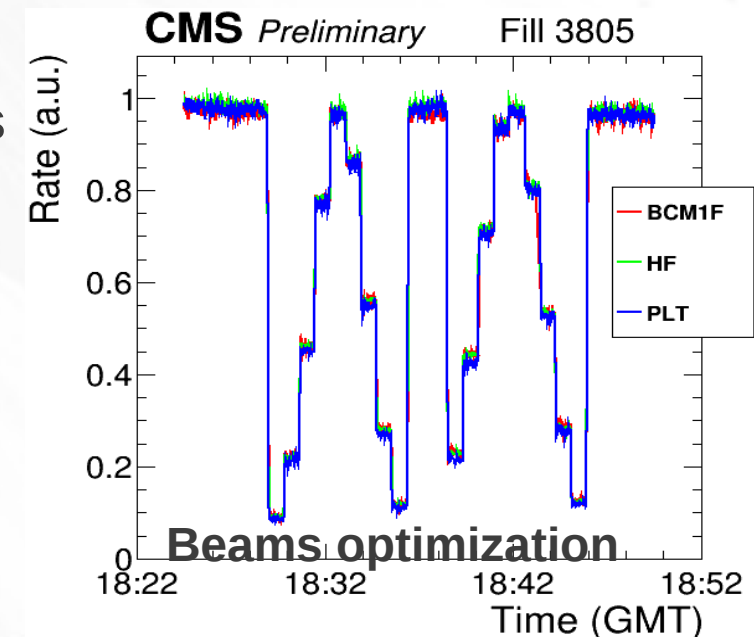
Some measurements of Machine Induced background in M.Hempel talk.

BCM1F as Luminometer

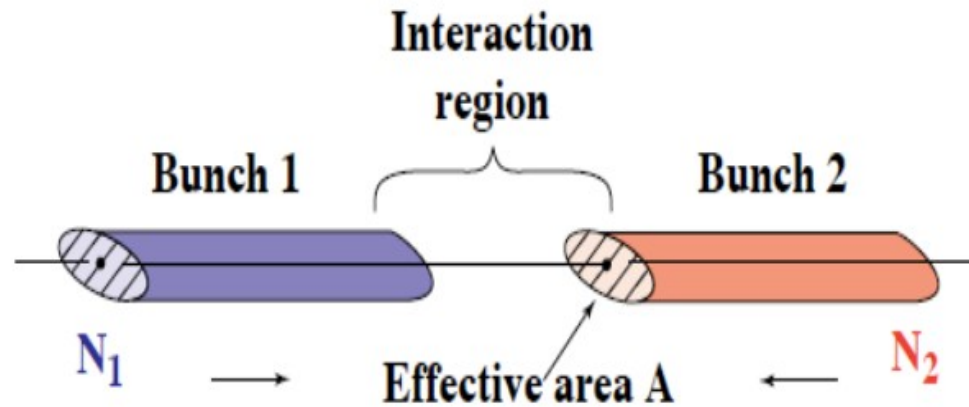
- **Luminosity (L)** is a key quantity of the collider, which allows to determine absolute cross section (the cross section, σ) from the observed rate in the detector (the rate, R):

$$R = \sigma L$$

- Fast diamond sensor response allowed to use BCM1F as a luminometer even with 25 ns bunch spacing in the LHC Run II.
- Rates are measured with fast backend electronics - Realtime Histogramming Unit (RHU) developed in DESY Zeuthen:
 - 6.25 binning \rightarrow 25 ns are saved in 4 bins
- From first days of operation CMS Luminometers are in a good agreement:
 - Fast Beam Conditions Monitor (BCM1F)
 - Forward calorimeter (HF)
 - Pixel Luminosity Telescope (PLT)



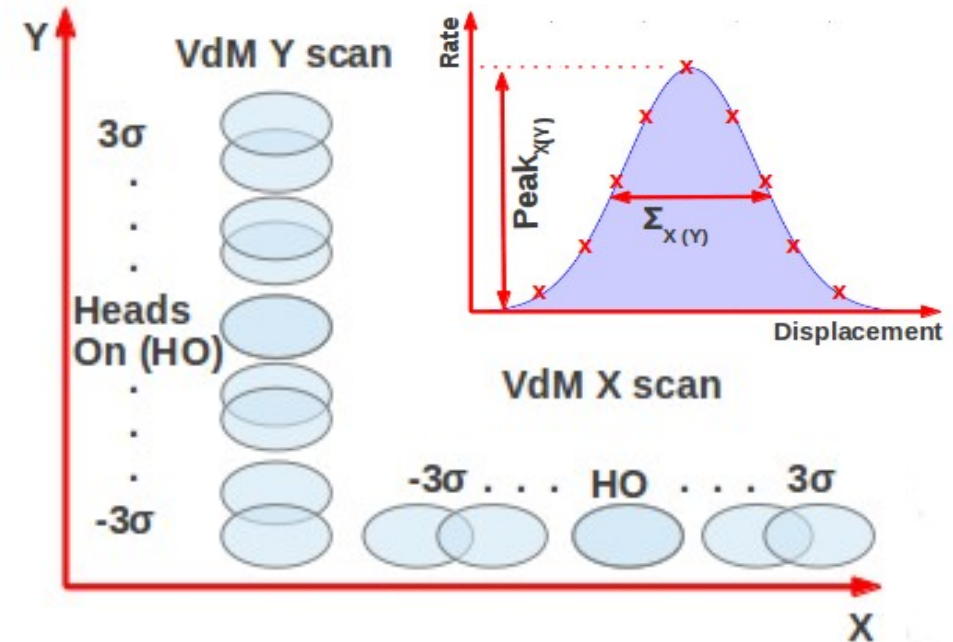
Calibration of BCM1F as luminometer



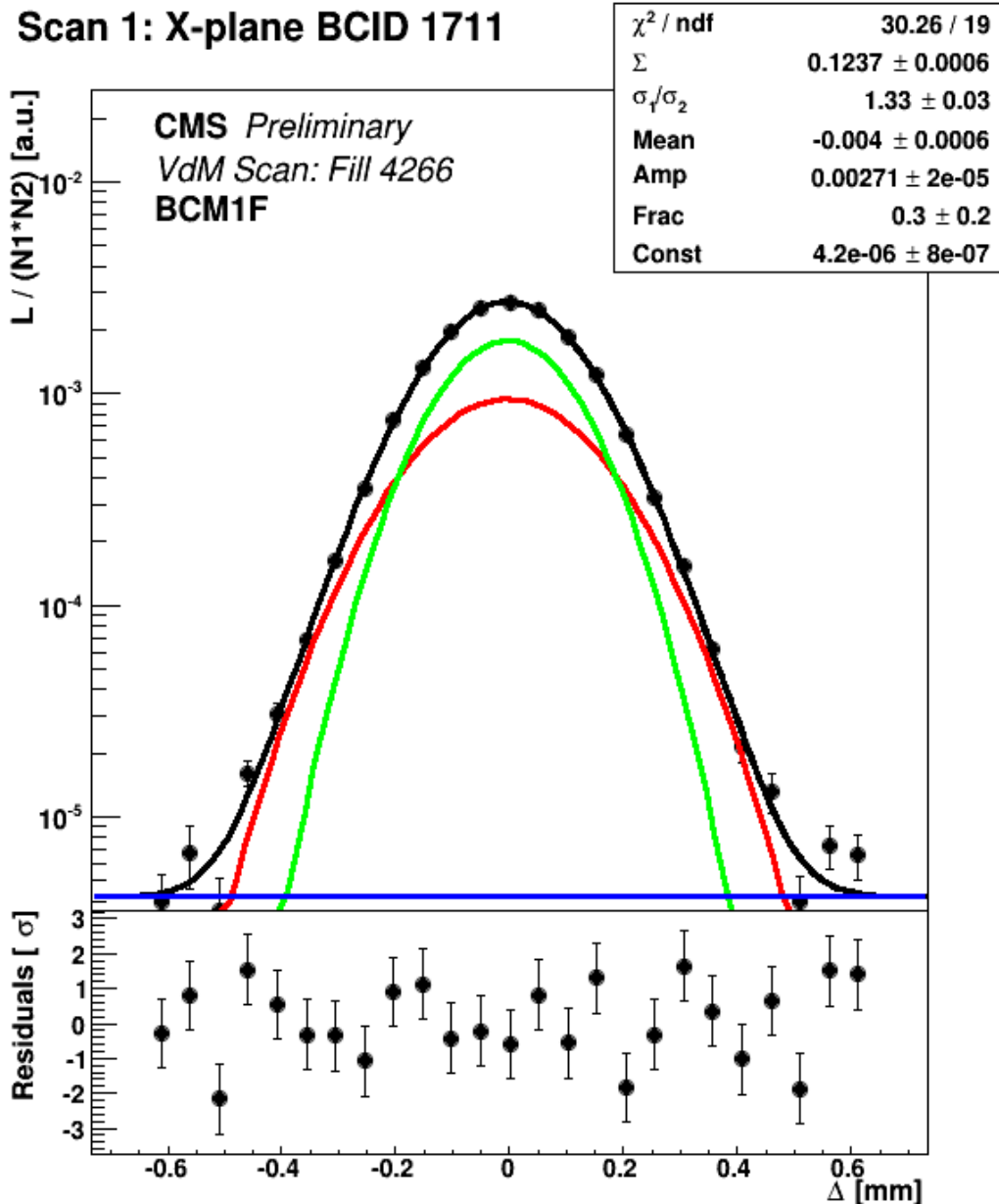
$$L = N_1 N_2 f n_b / A_{eff},$$

where N_1, N_2 - number of protons in beams 1 and 2, f - LHC orbit frequency, n_b - number of colliding bunches, A_{eff} - effective area.

- **Van der Meer scan method** proposed by Simon van der Meer: determine A_{eff} by measuring rates as a function of the beams displacement. Scans obtained in X and Y planes separately.
- Assuming Gaussian beams: convolution of two Gaussians is itself Gaussian. From VdM scans determine sigma («CapSigma» Σ_x and Σ_y) and amplitudes ($Peak_x$ and $Peak_y$).



Visible cross section measurement



- Analysis framework is used to fit beam overlap and calculate visible cross section - the effective cross-section seen by the lumi-nometer:

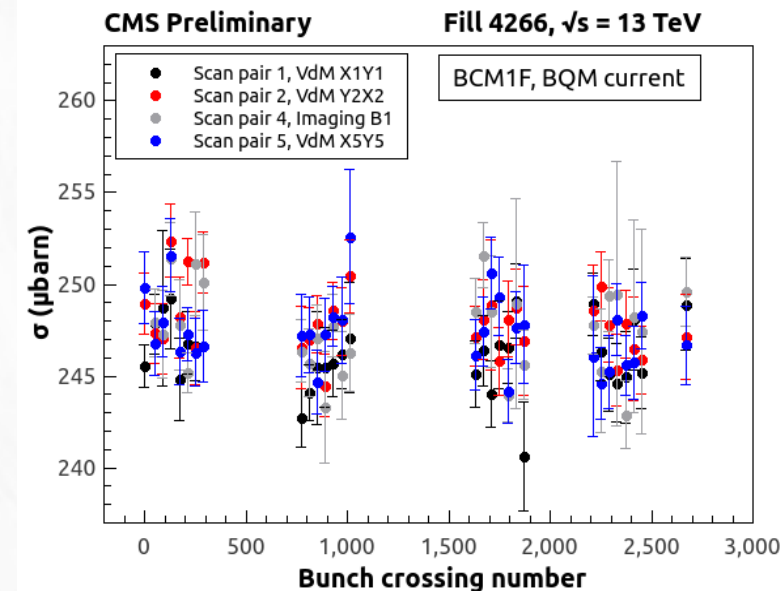
$$A_{eff} = 2 \pi \Sigma_1 \Sigma_2,$$

$$\sigma_{vis} = \frac{2 \pi \Sigma_X \Sigma_Y}{N_1 N_2 f n_b} \left(\frac{Peak_X + Peak_Y}{2} \right).$$

- The distribution is fitted with a Double Gaussian + Constant fit (fit functions are shown in green, red and blue and resulting function in black).
- The errors shown are statistical only.

Summary

- Upgraded Fast Beam Conditions monitor based on 24 diamond sensors is successfully installed in the end of 2014.
- From first days of LHC operation in 2015 BCM1F provides online bunch by bunch machine induced background and luminosity measurements.
- **The BCM1F is official CMS luminometer for physics for 50 ns data taking period (June-July 2015).**
- Due to radiation damage MIP peak position lost between 10% and 60% from initial position. Increasing of HV would compensate these losses.
- HV instability and long pulses are issues to solve.



Acknowledgements

- Great thanks to the German-Israel Foundation (GIF), the Brandenburg University of Technology (BTU) and DESY-Zeuthen for support!
- Also to Prof. Wolfgang Lohmann and whole CMS BRIL group for interesting ideas, enthusiasm and motivation!

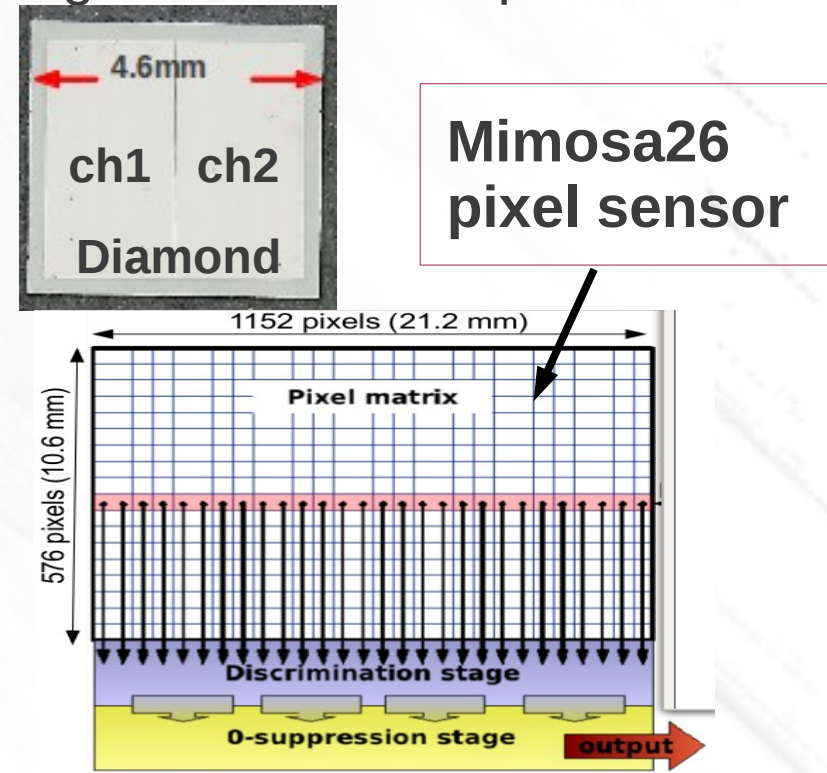
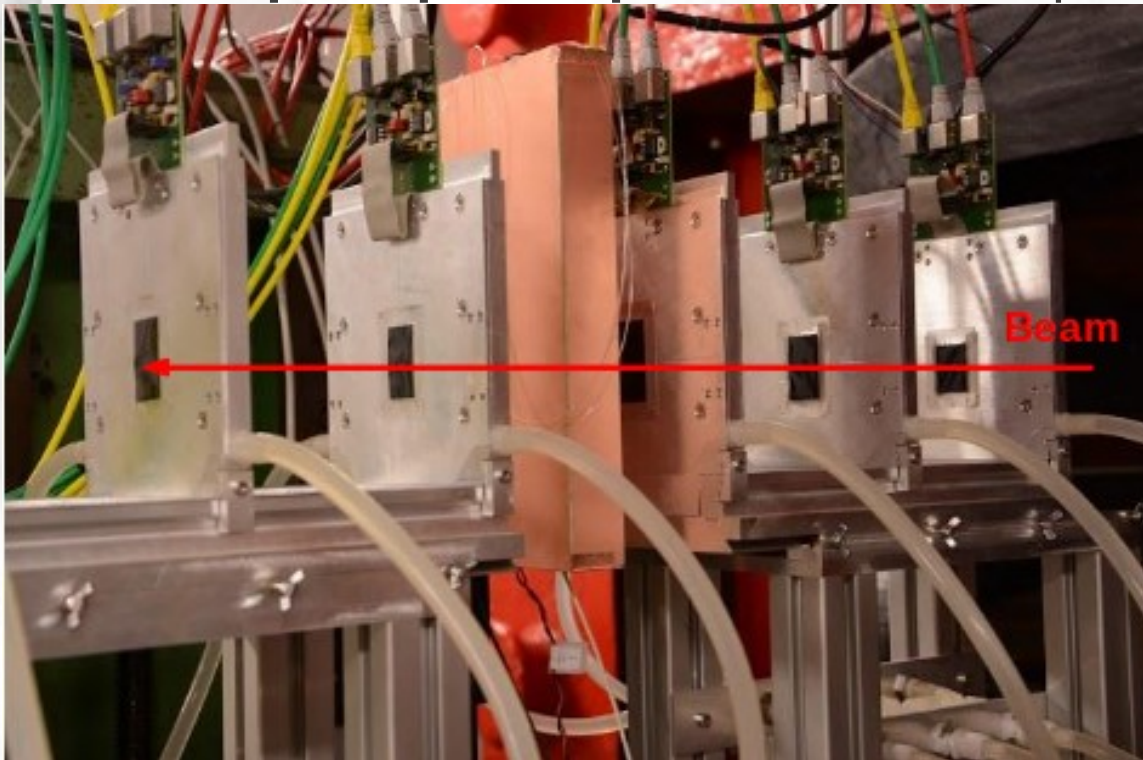
Thank you for attention!

Testbeam and sensors



EUDET Telescope - tracking device designed for detector prototype characterisation at the test beam:

- Active area of the telescope - **6 Mimosa26 pixel sensors**.
- **6 space points per track**, Track pointing resolution $< 10 \mu\text{m}$.



DESY II, TB area 22, 5 GeV electrons, 100 Hz rate.